

Plumbing the Arduino

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(and a cast of thousands, including Matt Jadud,
Christian Jacobsen, Omer Kilic, Carl Ritson...)

A brief history lesson

- In the 1980s, INMOS created the Transputer
- ... and an unusual programming language, called occam
- Further developed at Kent in the 1990s and 2000s: occam-pi
- Here's what it looks like...

C++:

```
doThing();  
doOtherThing();
```

occam:

```
SEQ  
  doThing()  
  doOtherThing()
```



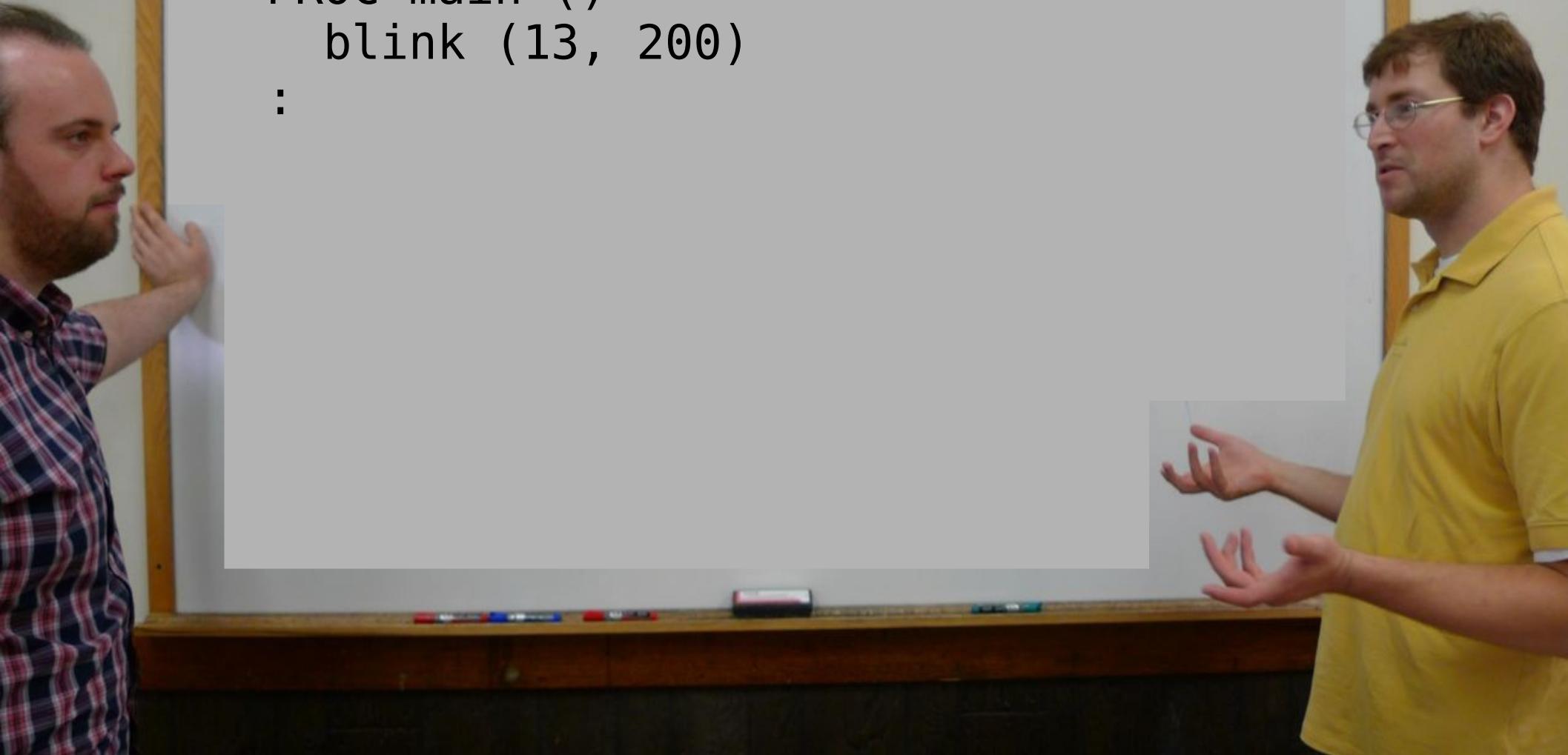
```
PROC main ()  
  WHILE TRUE  
    SEQ  
      digitalWrite (13, HIGH)  
      delay (200)  
      digitalWrite (13, LOW)  
      delay (200)  
    :
```

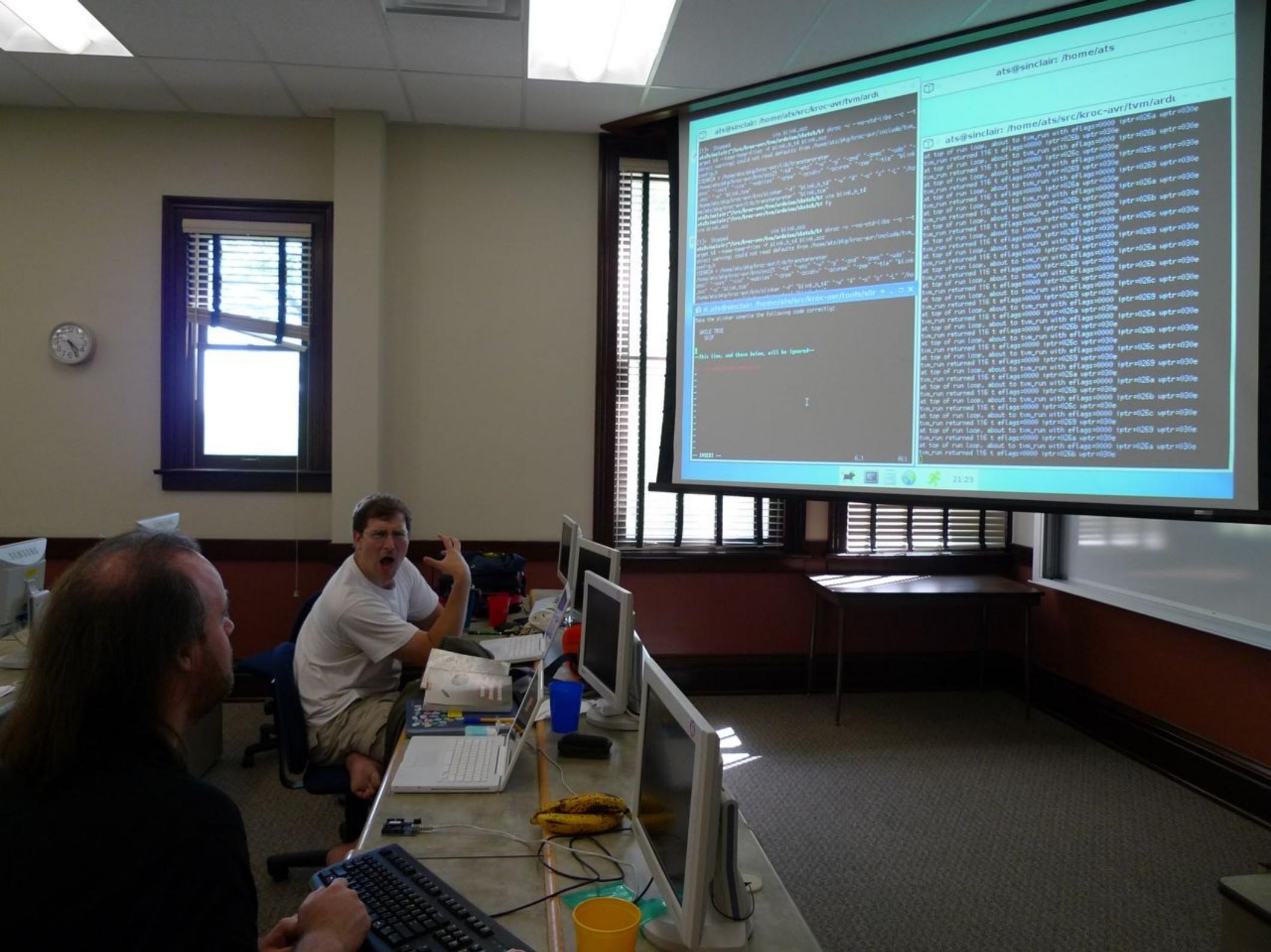


```
PROC blink (VAL INT pin, period)
  WHILE TRUE
    SEQ
      digitalWrite (pin, HIGH)
      delay (period)
      digitalWrite (pin, LOW)
      delay (period)
    :
PROC main ()
  blink (13, 200)
:
```



```
PROC main ()  
    blink (13, 200)  
:
```





```
ats@sinclair: /home/ats
```

```
at top of run loop, about to tw.RUN with efflags=0x000 iptr=0x26a uptr=0x00e
```

```
tw.RUN returned 116 t efflags=0x000 iptr=0x26b uptr=0x00e
```

```
at top of run loop, about to tw.RUN with efflags=0x000 iptr=0x25c uptr=0x00e
```

```
tw.RUN returned 116 t efflags=0x000 iptr=0x25d uptr=0x00e
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```

```
ats@sinclair: /home/ats/src/kroc-avr/tvm/ardi
```

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```

```
at top of run loop, about to tw.RUN with efflags=0x000 iptr=0x25c uptr=0x00e
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```

occam:

PAR

X

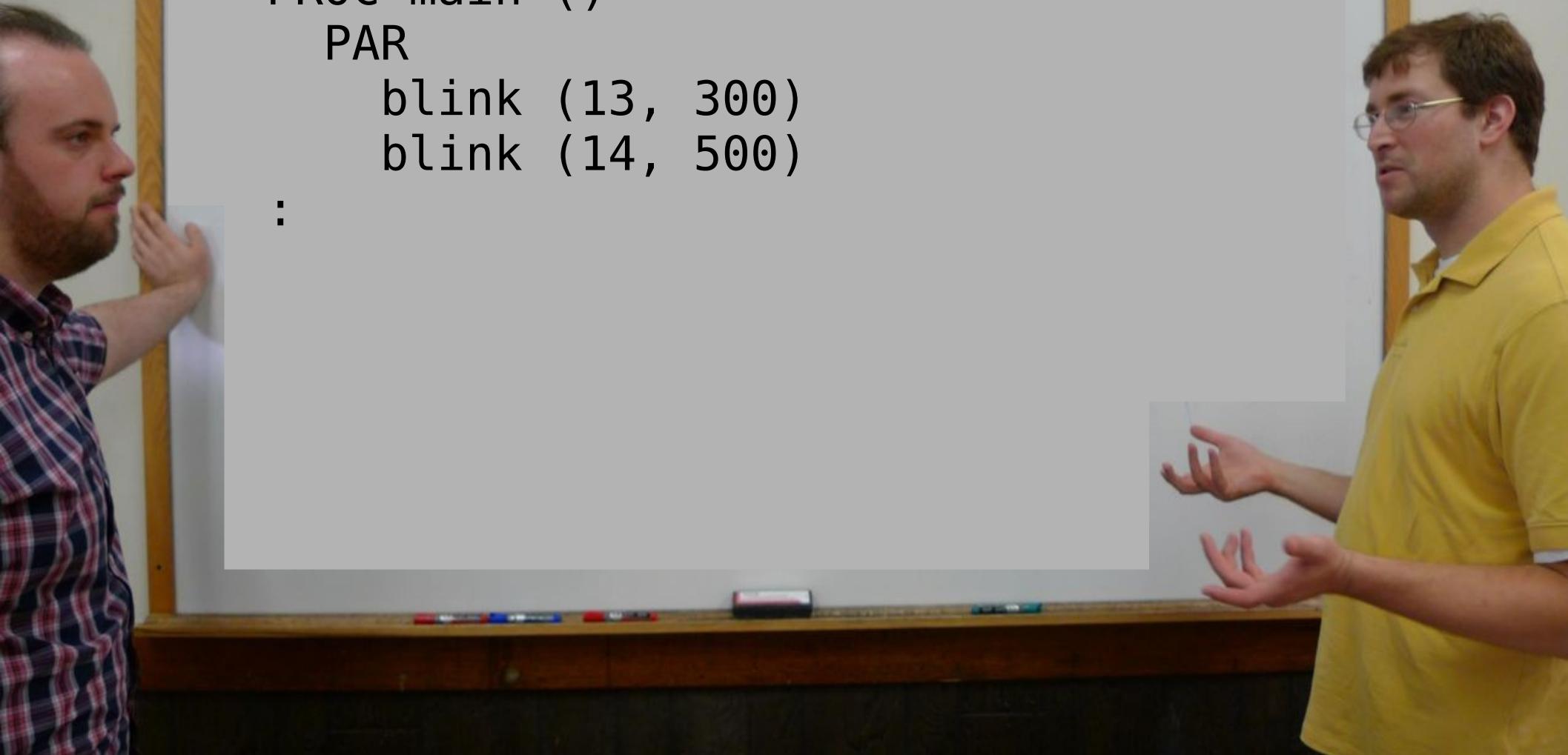
y

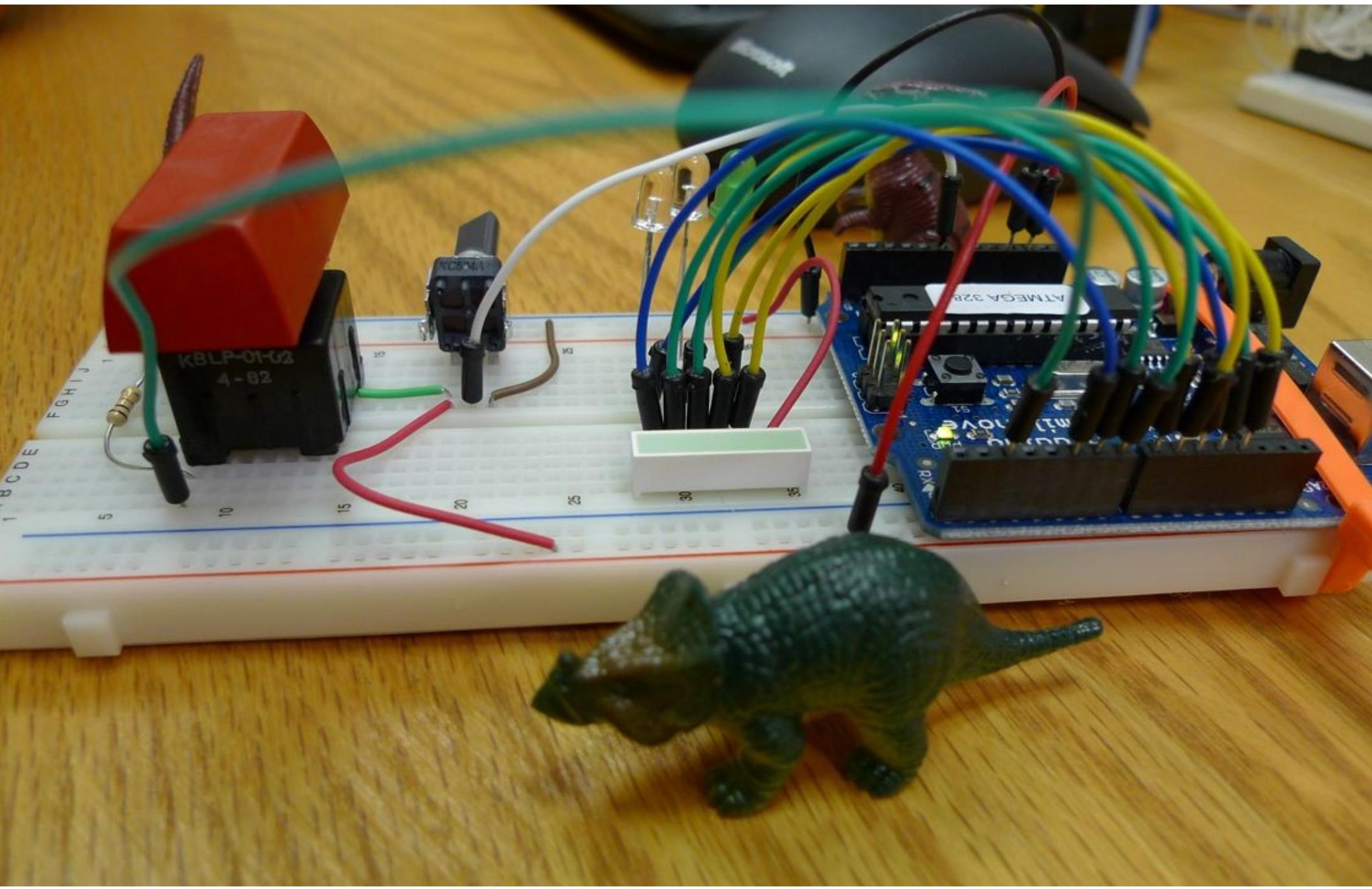
C++:

??!?!?!



```
PROC main ()  
PAR  
    blink (13, 300)  
    blink (14, 500)  
:
```



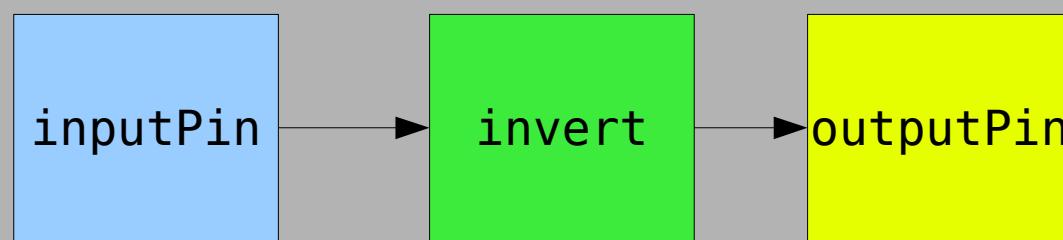


This is a channel.



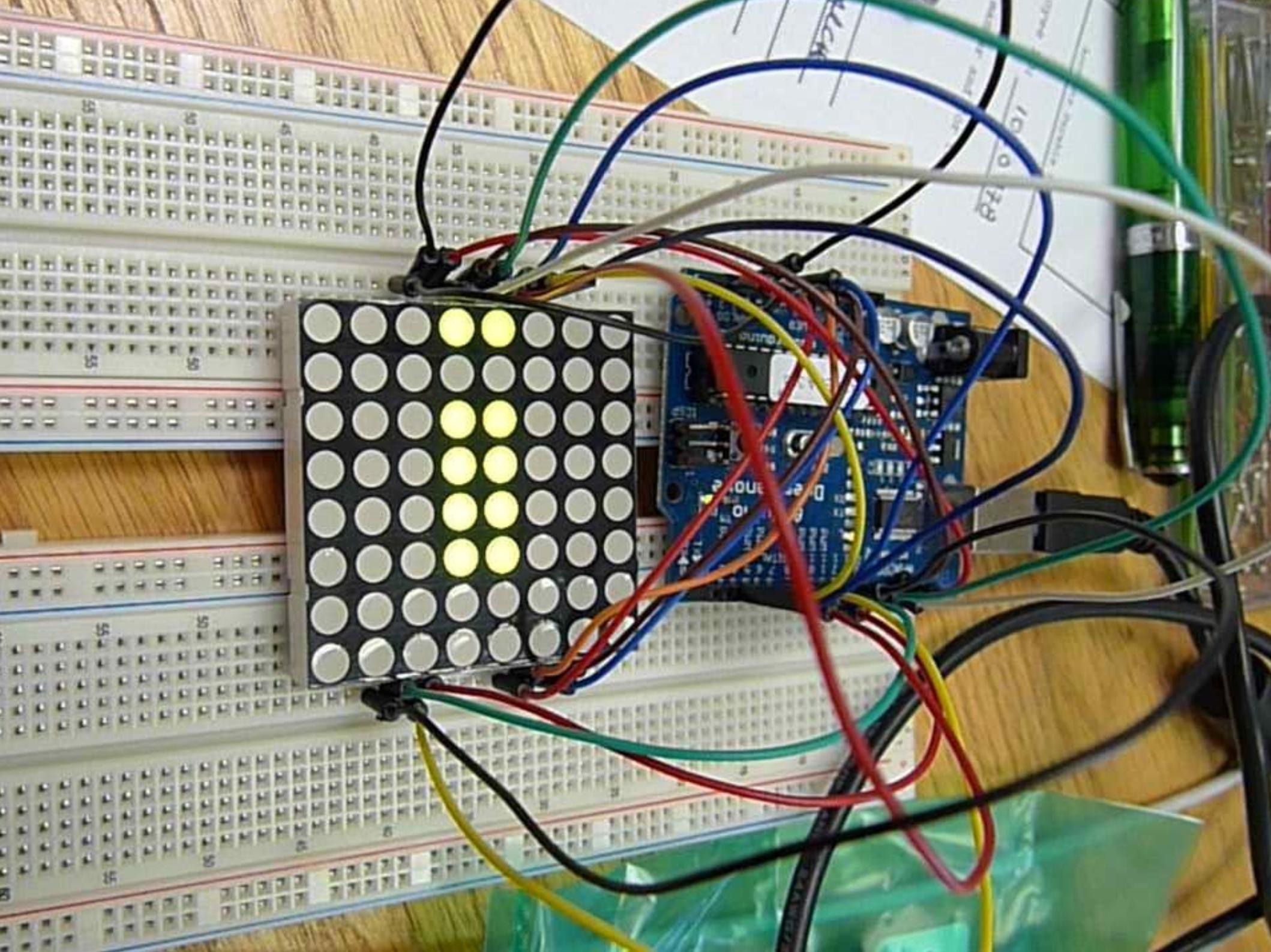




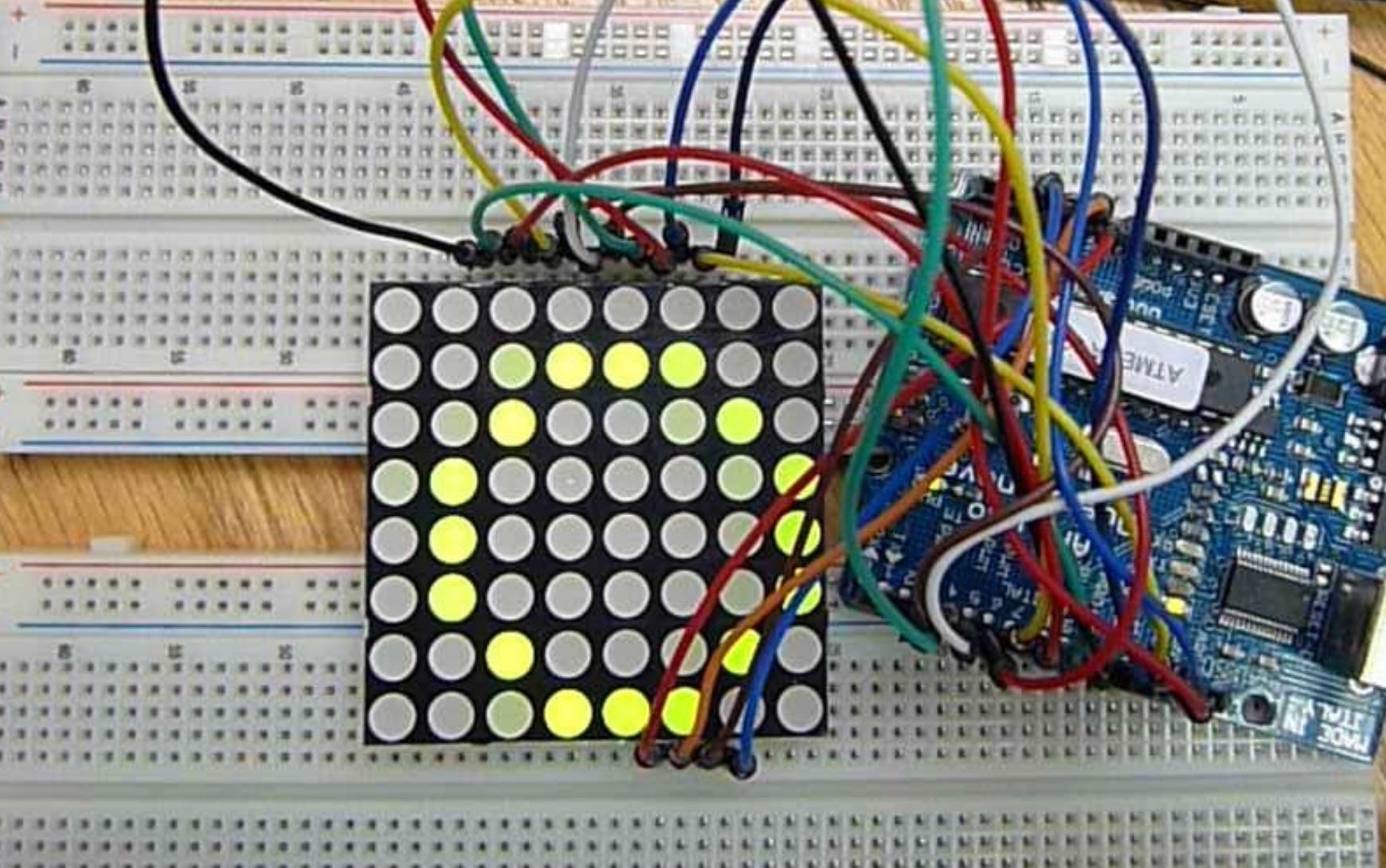


Concurrency in action

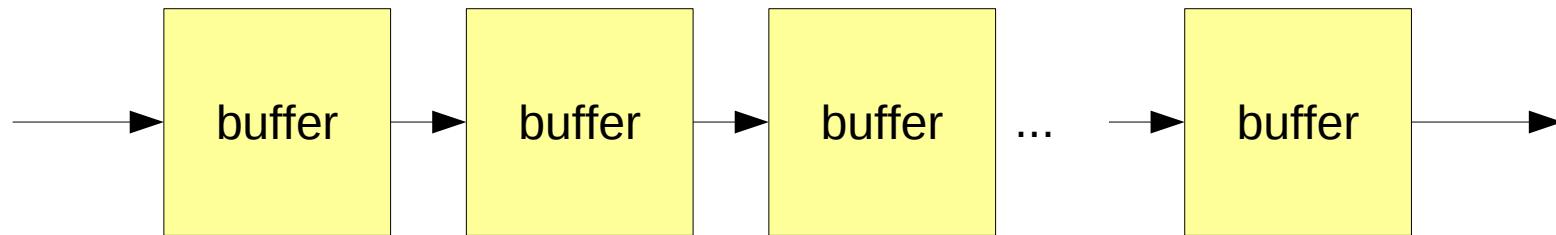
- We call this “process-oriented programming”
- Build your program out of little, isolated components, and connect them together
- **Plumbing** is a library of ready-made components (like `inputPin`, `invert` and `blink`) for the Arduino



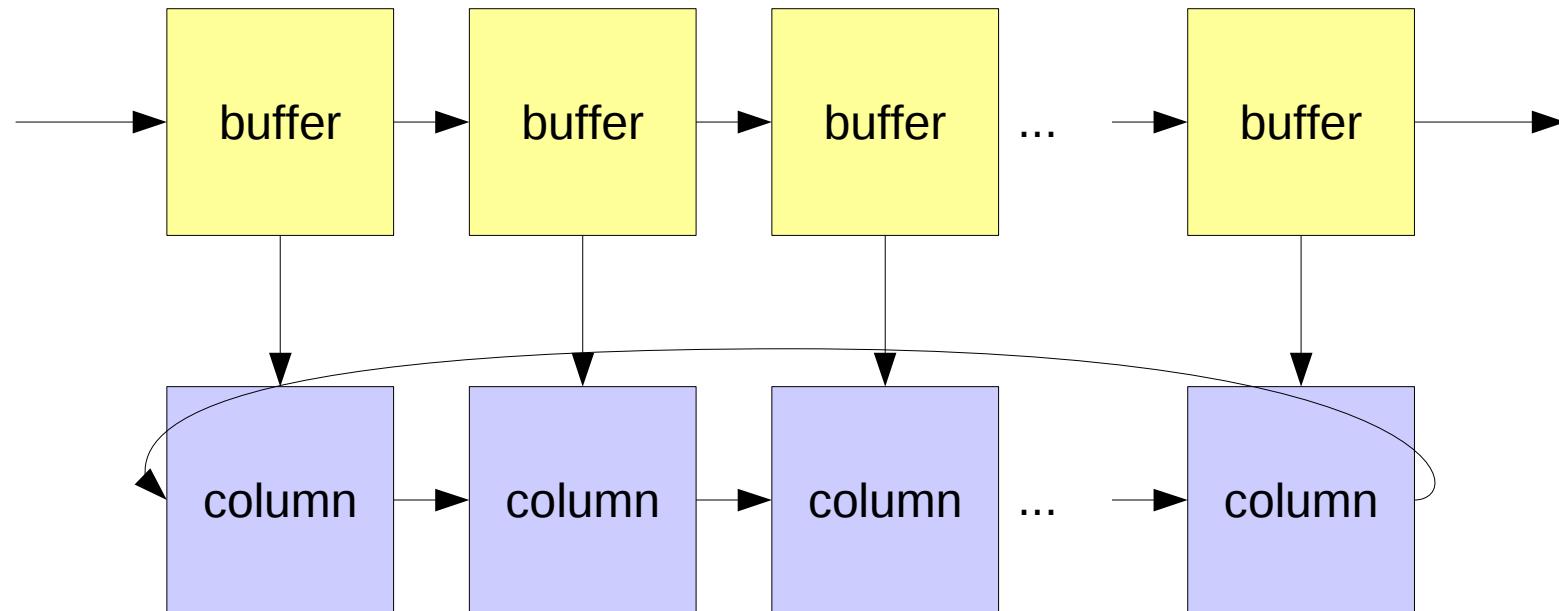
- CLOUD
- KESSELE
- ALARM
- TURBO
- UPS CO
- CEN
- GRUP
- PUM
- ALD
- (PUM)



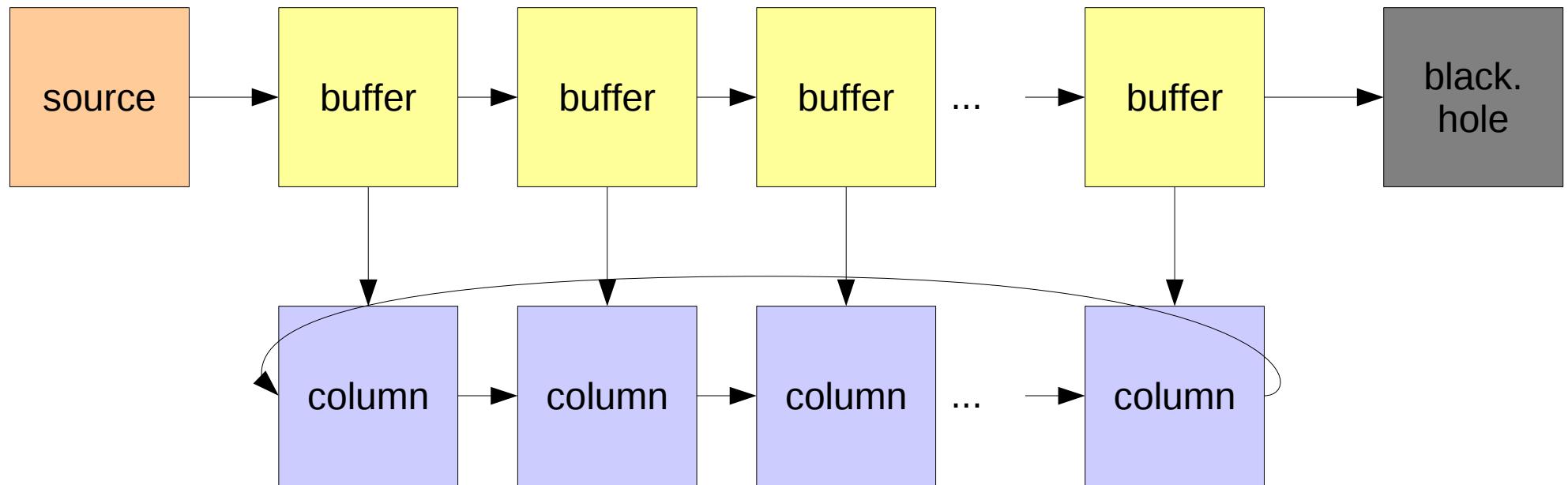
How does that work?

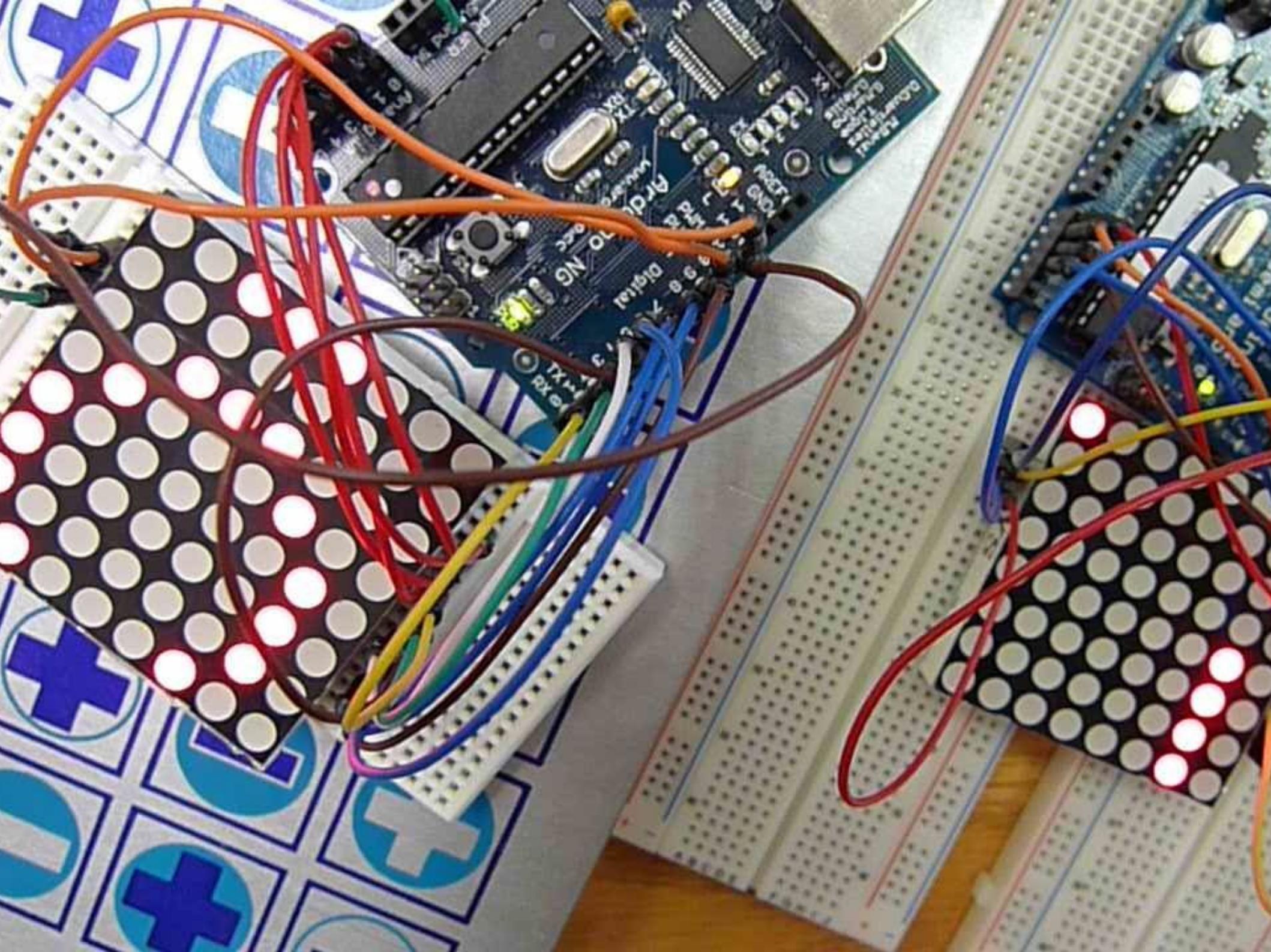


How does that work?

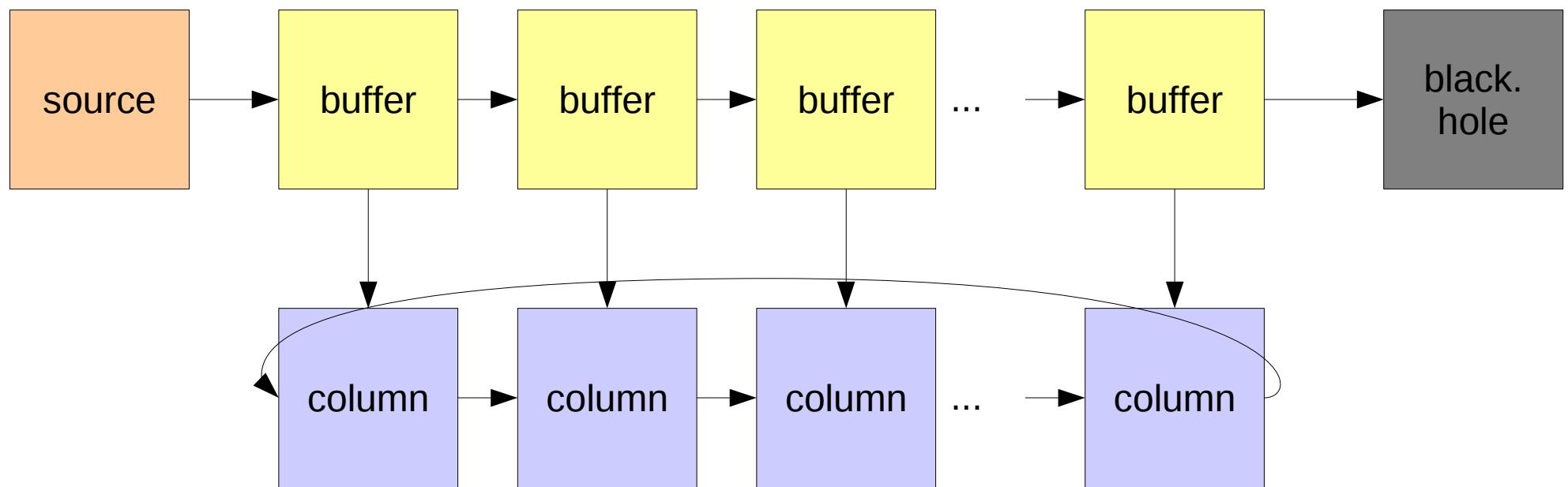


How does that work?

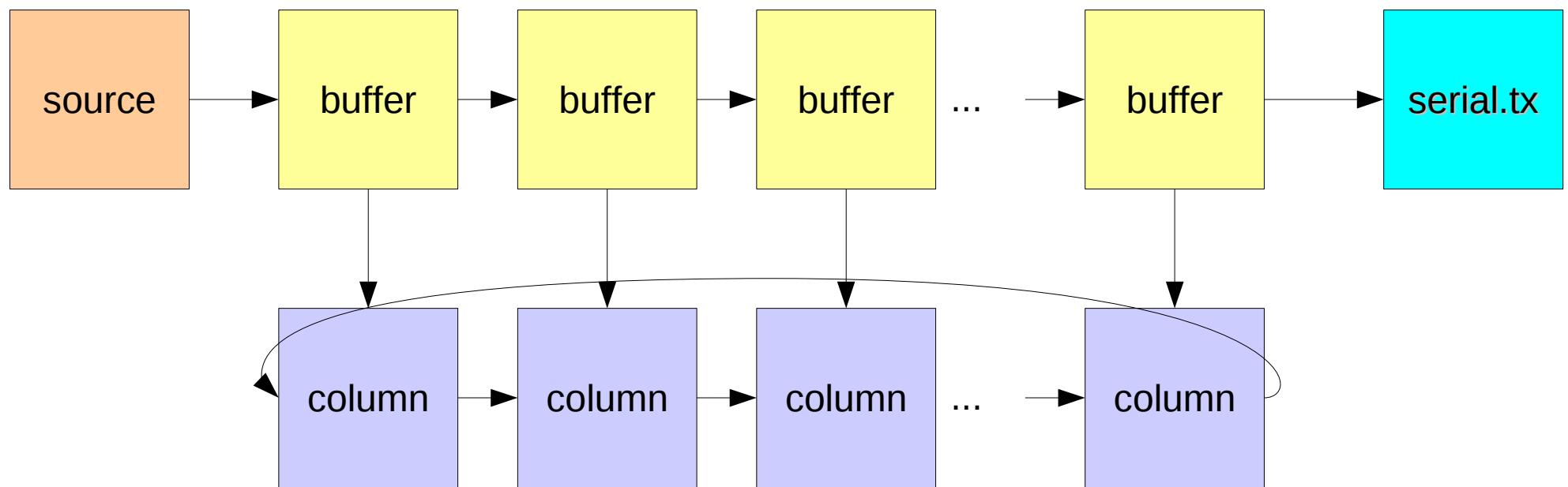




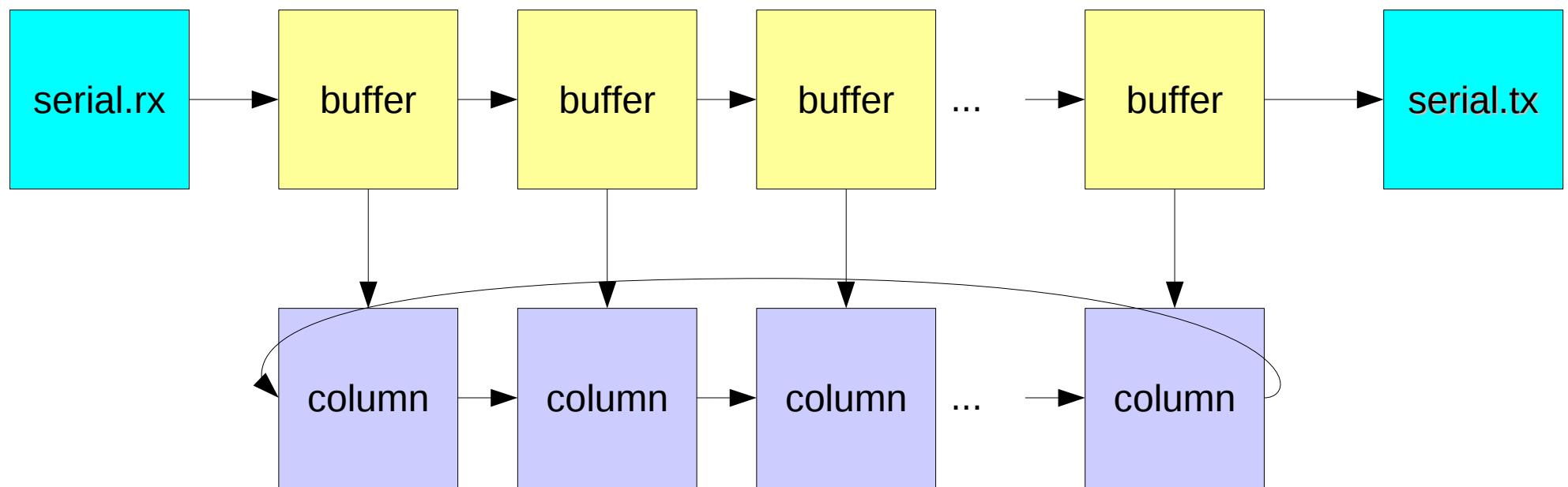
Distributed embedded system

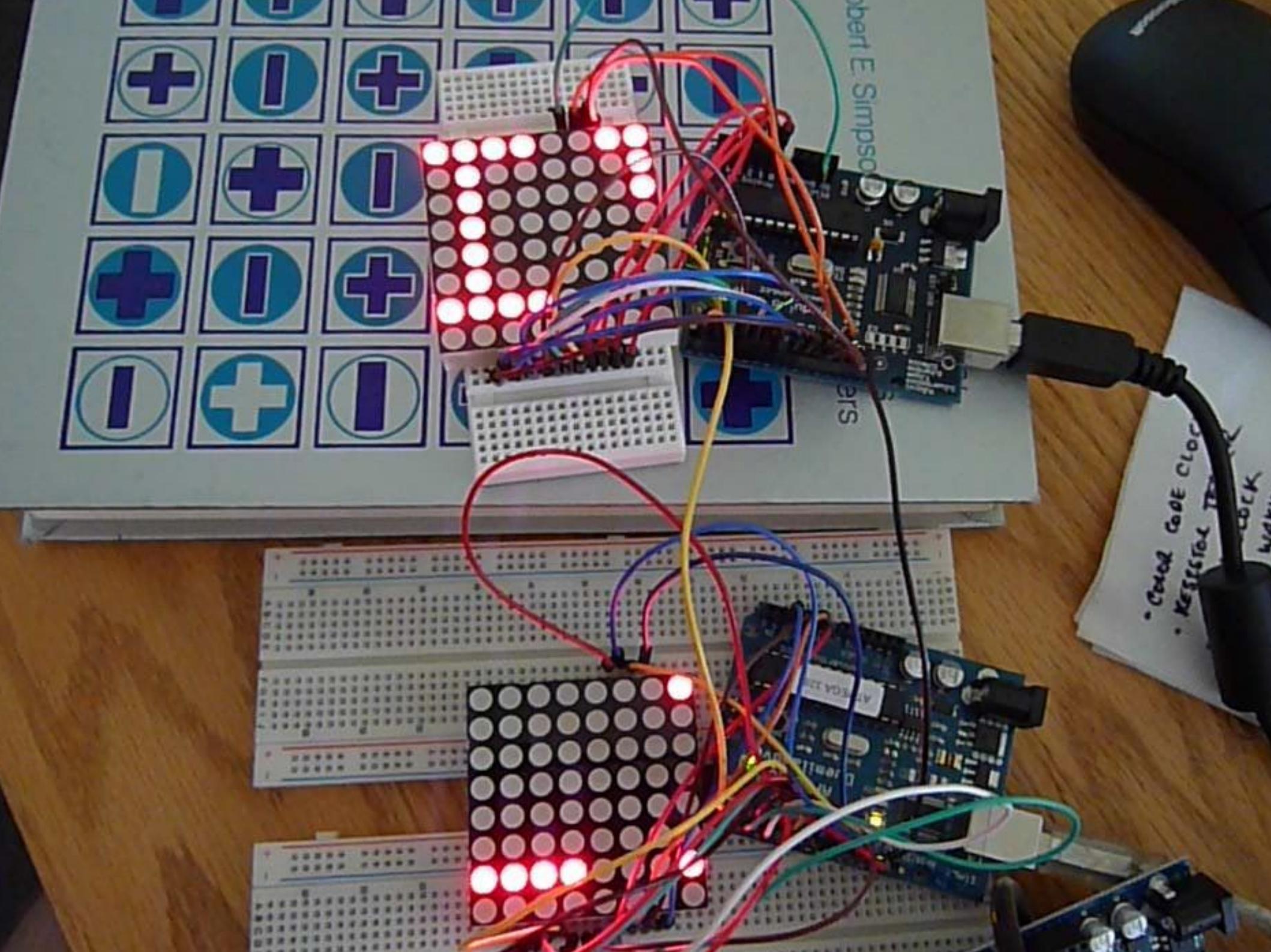


First node



Other nodes

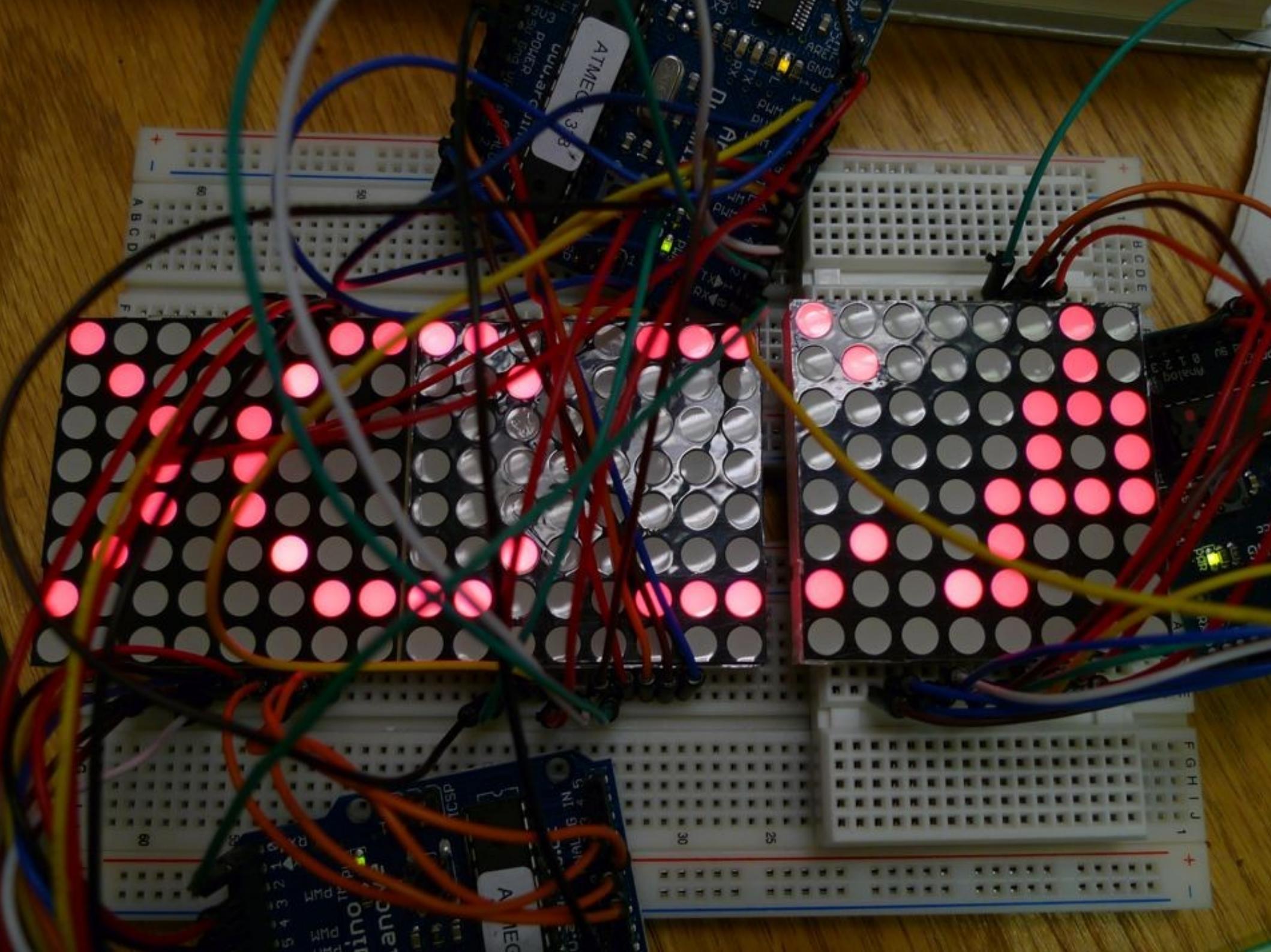


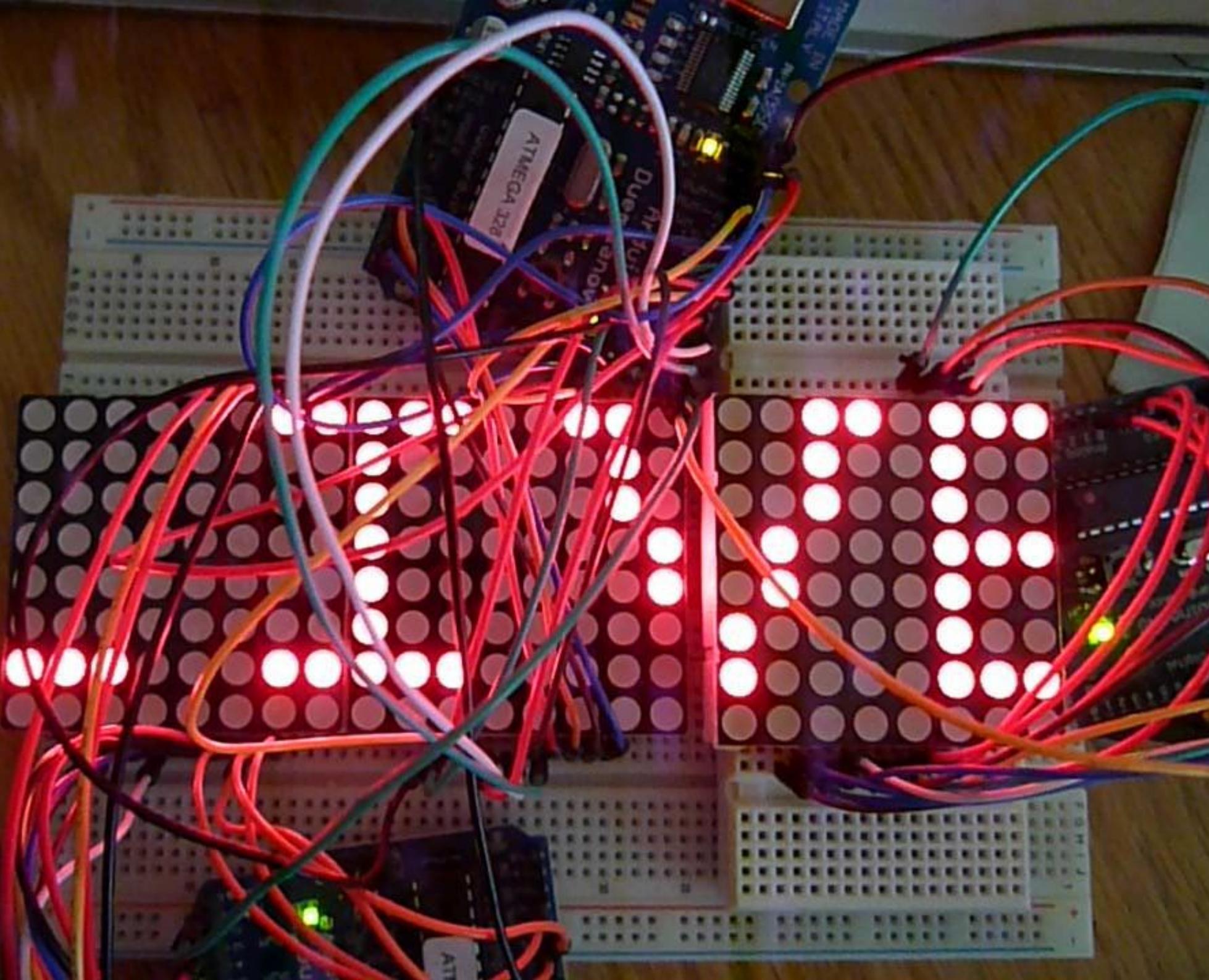


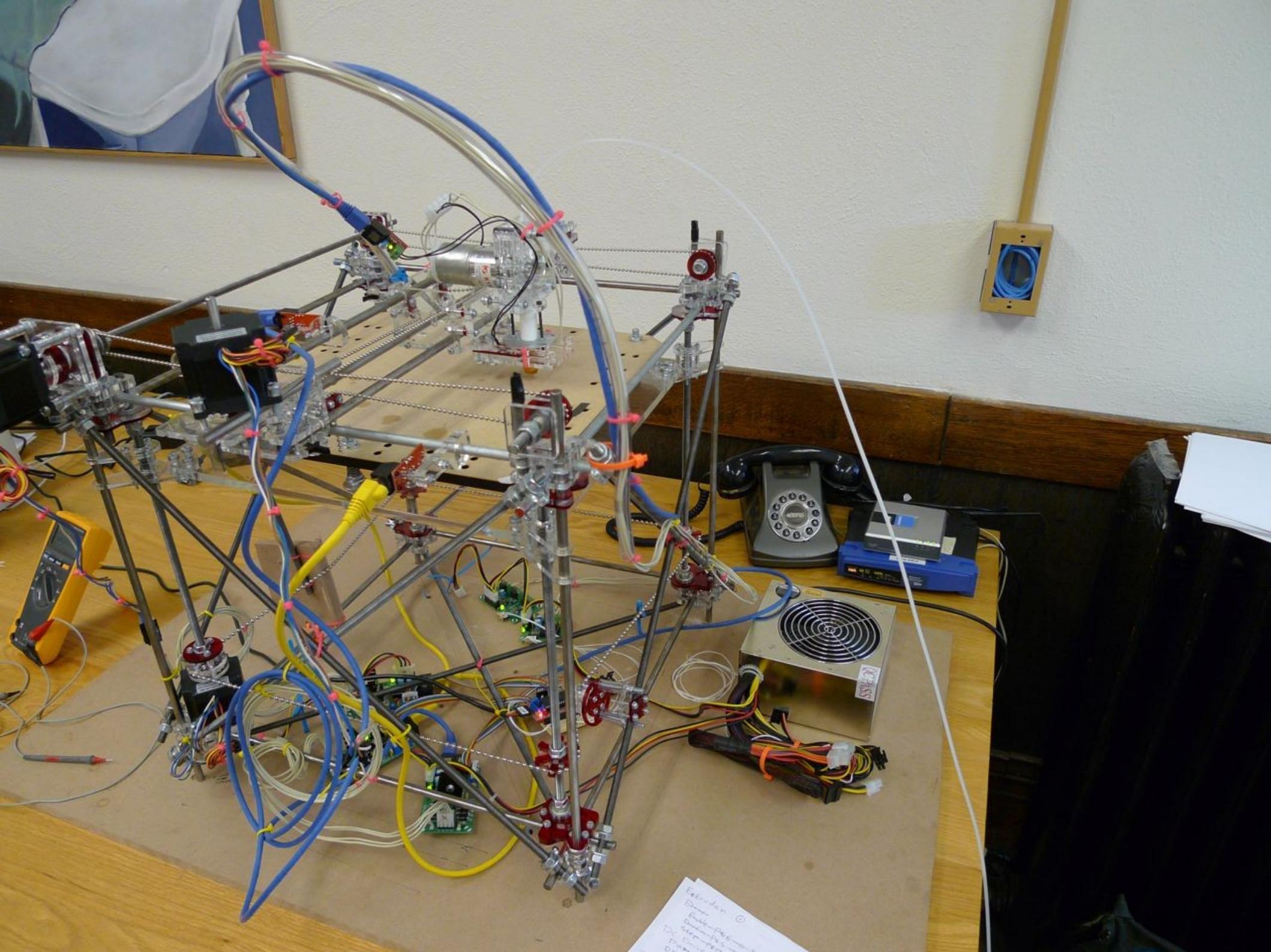
S

• Clock Gate Clock
• KETTERER

WAVES



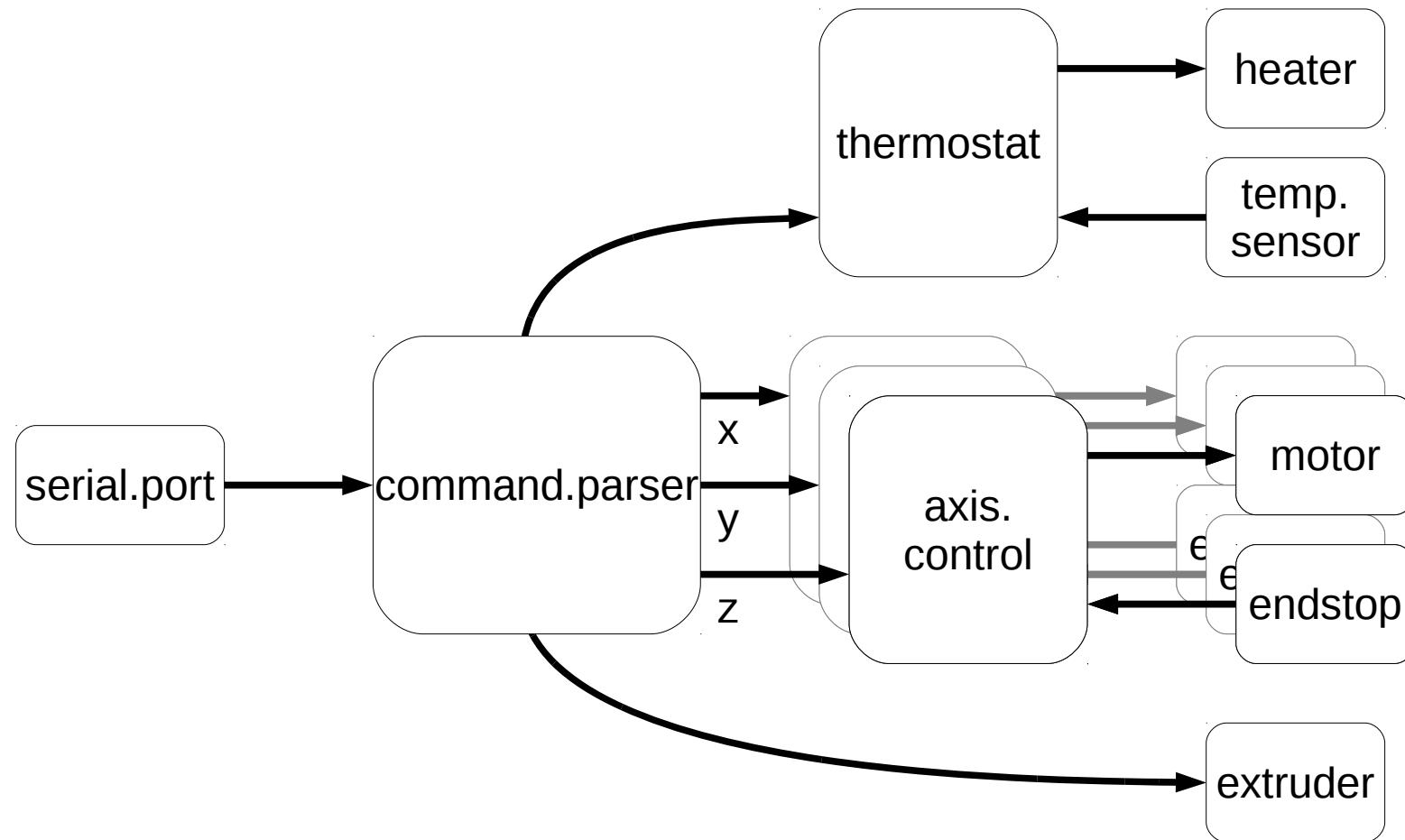




The RepRap

- X, Y and Z axes with steppers and endstops
- Print head with heater, temperature sensor and extruder motor
- Serial interface to accept commands from a host computer

Plumbing the RepRap



How do I learn more?

- Read the book!
- Available from our web site along with the software (all open source):
<http://concurrency.cc/>
- For more about occam-pi:
<http://occam-pi.org/>
- Thanks – any questions?

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